School of Information Technology Indian Institute of Technology Kharagpur T60108: Soft Computing Applications

IT60108: Soft Computing Applications Class Test - III

Full Marks: 20 Session 2014 - 2015 Time: 20 minutes

- 1. Which of the following statement(s) is(are) not true.
 - (a) GA is an optimization technique
 - (b) GA is a probabilistic search technique
 - (c) GA always gives optimal solution
 - (d) For a problem if there is more than one optimal solutions, GA outputs all the solutions
- 2. GA algorithm is effective to solve only
 - (a) single objective optimization problems
 - (b) mixed integer programming problem
 - (c) optimization problems involved with discrete(integer) variables
 - (d) optimization problems involved with continuous (integer/real) variables
- 3. In Simple GA (SGA), which is/are not allowed.
 - (a) Repetition in the individual selected for mating pool
 - (b) Population sizes in each generations are to be varied
 - (c) Overlapping generations
 - (d) Two or more individuals with same fitness value
- 4. In the context of Simple GA(SGA), the convergence rate will increase, if
 - (a) the size of mating $pool(N_p)$ is comparable to that of the population size (N)
 - (b) from the mating pool of size (N_p) , if we create N offspring to be replaced all individual in the current population
 - (c) from the mating pool of size (N_p) , if we replace a large number of offspring and only N_p worst individuals in the current population of size N
 - (d) select N_p best individuals for mating to produce N individual for the next generation

- 5. In the context of Steady-State GA (SGA), which of the following statement(s) is/are true.
 - (a) Generation gap is small
 - (b) Convergence rate is high
 - (c) Gives better result than the Simple GA (SGA)
 - (d) It is susceptible to stagnation
- 6. If we compare SGA and SSGA, then
 - (a) the time for single iteration in SGA is more than in SSGA
 - (b) overall time of termination in SGA is more than in SSGA
 - (c) population diversity in SGA is far better than that of SSGA
 - (d) selection pressure in SGA is more than that of SSGA
- 7. Which of the following cannot be considered as a convergence criterion.
 - (a) There is no significant change in the average fitness value for an successive generations
 - (b) The execution of GA elapsed a pre-specified time T
 - (c) p percentage of N (where p is some positive constant and N is the size of the population) individuals are with the same fitness values
 - (d) Fitness values of all individuals are above than a certain threshold value
- 8. Which of the following statement is true.
 - (a) Binary coded GAs are faster than the real-coded GAs
 - (b) Binary coded GAs are accurate than the real-coded GAs
 - (c) All optimization problems can be encoded with binary-coded GA
 - (d) All GA parameters, which are applicable to binary-coded GA is also applicable to Order-GA
- 9. The length of chromosomes in binary-coded GAs, is decided by
 - (a) number of design variables
 - (b) range of values of design variables
 - (c) objective functions
 - (d) constraints
- 10. Which of the following is/are not valid chromosomes in order GA?
 - (a) 1 0 0 1 1 0 0 1
 - (b) 1 3 5 7 2 4 6 8
 - (C) A B D E A F H G
 - (d) 14.6 -23.4 177.23

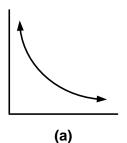
Answer: (a), (c), (d)

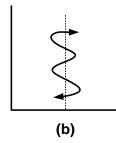
- 11. Out of the following crossover techniques, which do(es) not suffer(s) from "end point" problem.
 - (a) Single point crossover
 - (b) Uniform crossover
 - (c) Shuffle crossover
 - (d) Multi-point crossover
- 12. State whether the following statements are true or false.
 - (a) The most expensive operation in GA is the selection of individual for mating pool creation
 - (b) Mutation operation is not mandatory in any GA-based problem solving
 - (c) The number of GA loop will increase if the population size is increased
 - (d) Even we can implement Simple GA(SGA) without performing selection operation

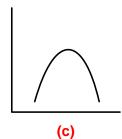
Answer: (a): FALSE, (b): TRUE, (c): FALSE, (d): TRUE

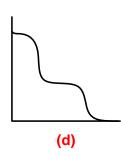
- 13. The purpose of the fitness evaluation operation is
 - (a) to check whether all individual satisfies the constraints given in the problem
 - (b) to decide the termination point
 - (c) to select the best individuals
 - (d) to identify the individual with worst cost function
- 14. Average fitness calculation can be used to
 - (a) understand whether the optimal solution(s) has been achieved
 - (b) termination of GA execution
 - (c) generation gap between two successive GA iteration
 - (d) whether the problem has been struck at local optima or not
- 15. Roulette-Wheel selection scheme is preferable when
 - (a) fitness values are uniformly distributed
 - (b) fitness values are non-uniformly distributed
 - (c) needs low selection pressure
 - (d) needs high population diversity
- 16. Which of the following statement is true in case of Rank-based selection scheme.
 - (a) Low population diversity, high selection pressure
 - (b) Low population diversity, low selection pressure
 - (c) High population diversity, low selection pressure
 - (d) High population diversity, high selection pressure

- 17. High selection pressure is desirable, when we need
 - (a) faster termination of the GA
 - (b) near optimal solution
 - (c) there is no improvement in successive GA iteration
 - (d) fitness values are non-uniformly distributed
- 18. Tournament selection scheme is more preferable when
 - (a) population are with very diversified fitness values
 - (b) when fitness values are uniformly distributed
 - (c) when fitness values are not necessarily uniformly distributed
 - (d) under all the above situations
- 19. To make the G_p (Generation gap) a large value in Steady-state selection strategy, which of the following can be considered
 - (a) selection of individual according to their fitness values and replacement at random
 - (b) selection of individual at random and replacement according to the inverse of their fitness values
 - (c) selection of both parents and replacement according to the inverse values of their fitness values
 - (d) all of the above
- 20. In the following graphs, how an objective function (along y-axis) varies with input parameter (along x-axis) are shown. In which case(s), there is (are) no optimal solution(s) exist(s)?









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